

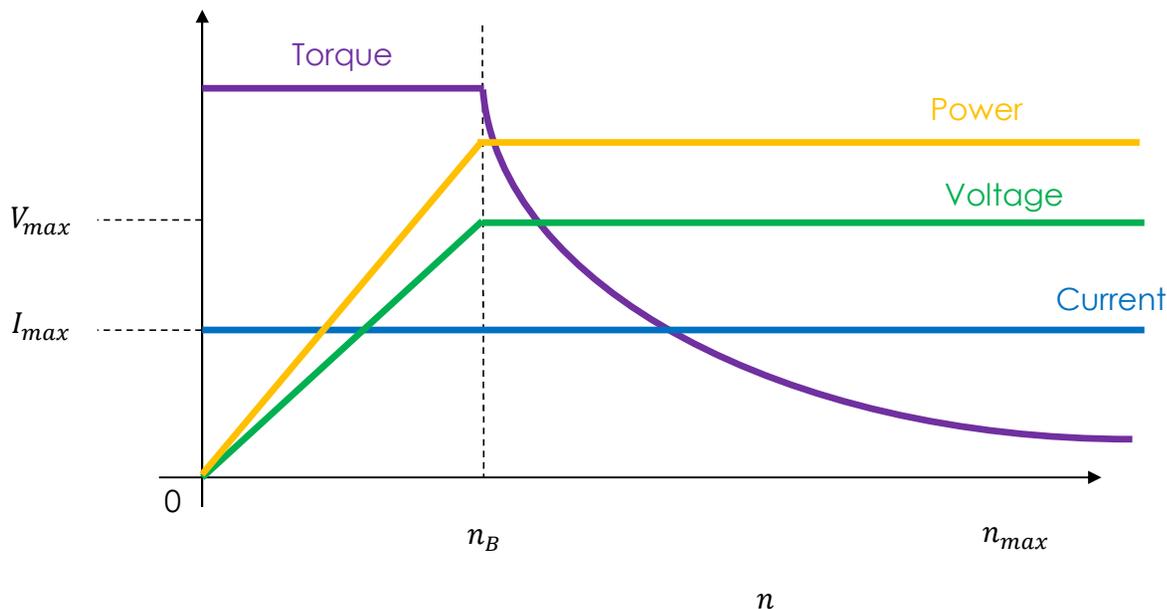


Electrify & Optimize: Revving Up E-Powertrain Design and Analysis

The Engineering Challenge

Battery, Motor, & Inverter Design Trade-offs

The Electrified Powertrain triplet (battery, motor, inverter) need to be designed and sized together:



V_{max} : Limits of battery

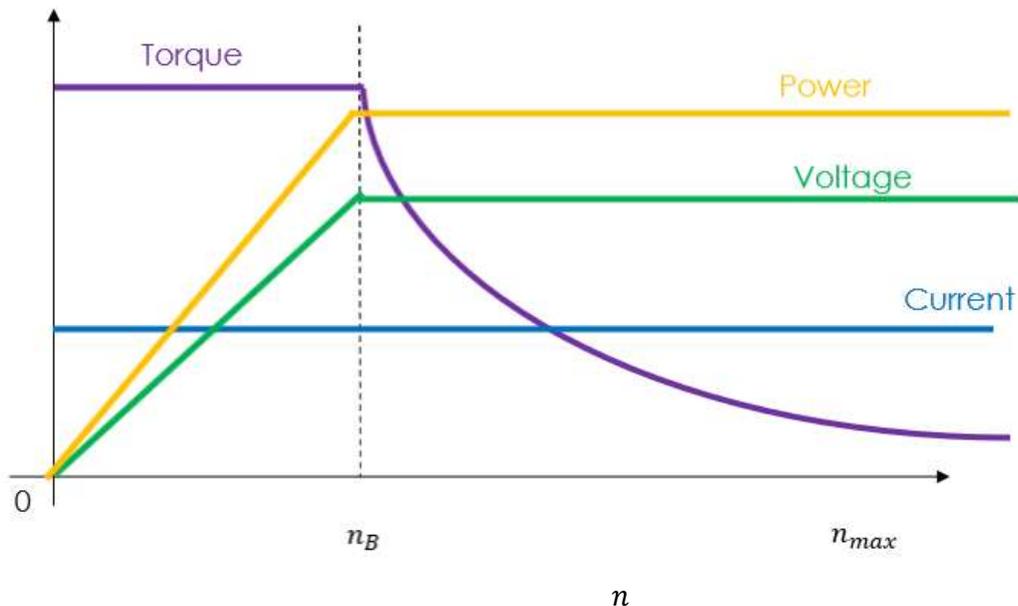
- Battery Chemistry
- N_{Series}

I_{max} : Limits of battery and motor

- $N_{Parallel}$
- Motor thermal security

Battery, Motor, & Inverter Design Trade-offs

The Electrified Powertrain triplet (battery, motor, inverter) need to be designed and sized together:



V_{max} : Limits of battery

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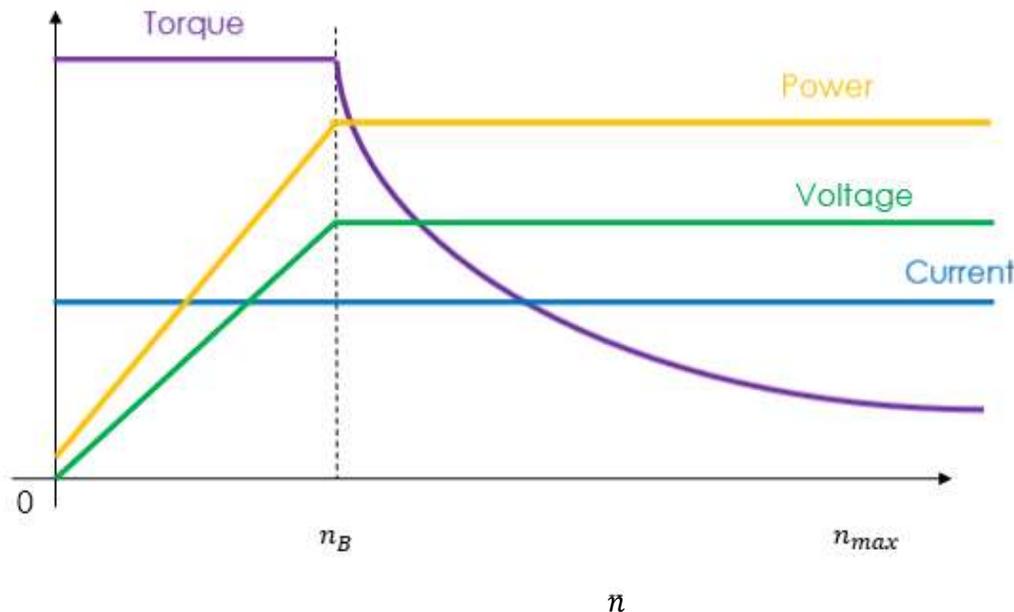
I_{max} : Limits of battery and motor

- $N_{Parallel}$
- Motor thermal security

What if: Increased Battery Voltage?

Battery, Motor, & Inverter Design Trade-offs

The Electrified Powertrain triplet (battery, motor, inverter) need to be designed and sized together:



V_{max} : Limits of battery

- Battery Chemistry
- N_{Series}

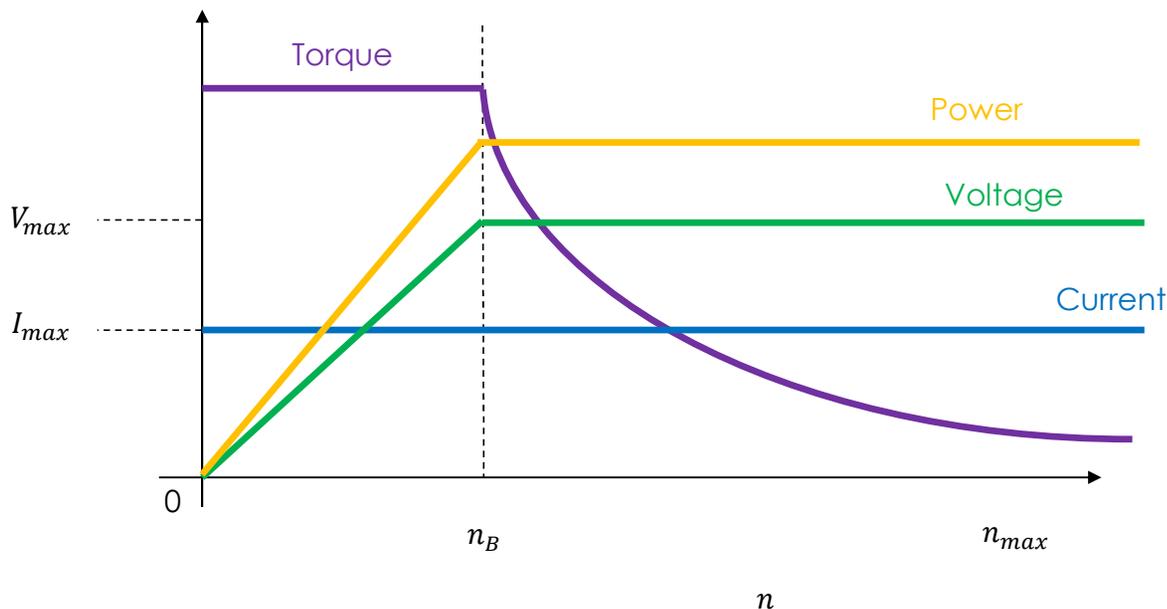
I_{max} : Limits of battery and motor

- $N_{Parallel}$
- Motor thermal security

What if: Improved motor cooling?

Battery, Motor, & Inverter Design Trade-offs

The Electrified Powertrain triplet (battery, motor, inverter) need to be designed and sized together:



At what cost?

- More expensive
- Heavier (worse BEV efficiency)

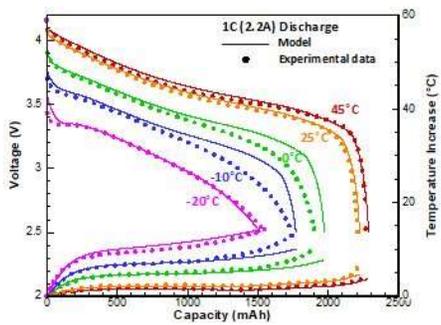
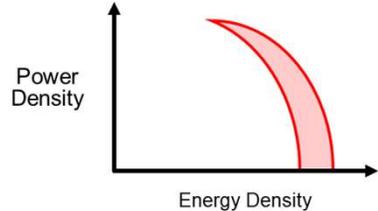
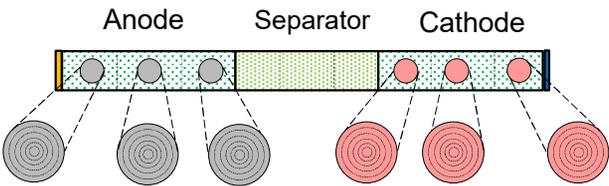
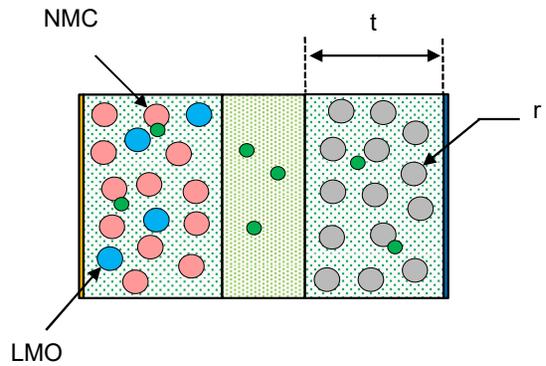
How can we study all of these tradeoffs together???

Solution Introduction

GT-AutoLion

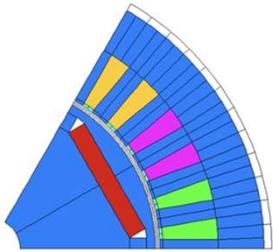


Performance
Degradation
Safety

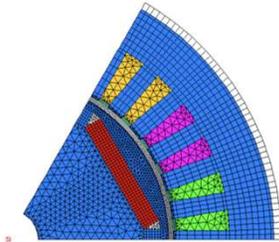


GT-FEMAG

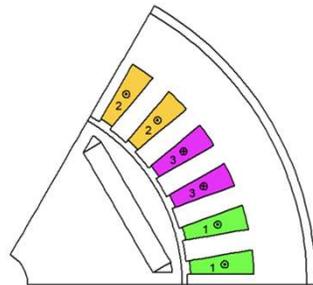
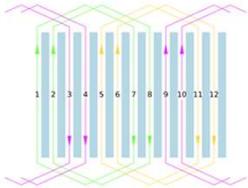
GT-FEMAG is a 2D Finite Element simulation of electromagnetics for motor design



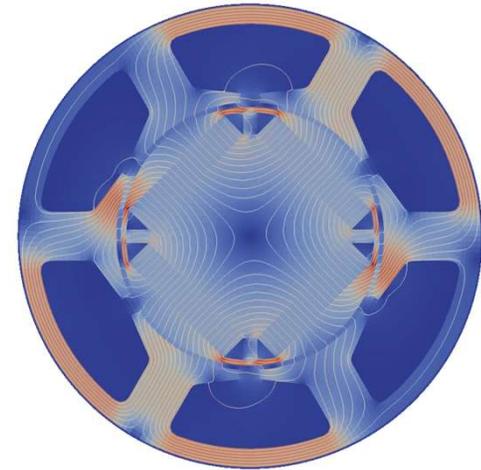
Flexible Geometry Definition



Industry-leading mesh technology



Flexible Winding Layouts



2D Magnetic Flux

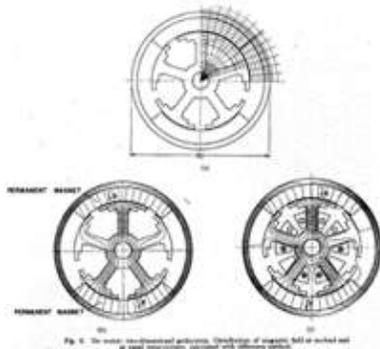
What is FEMAG?

2D Finite Element simulation of electromagnetics for motor design

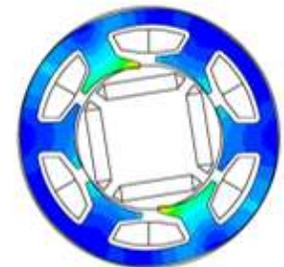
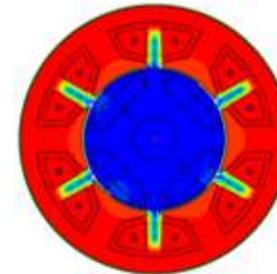
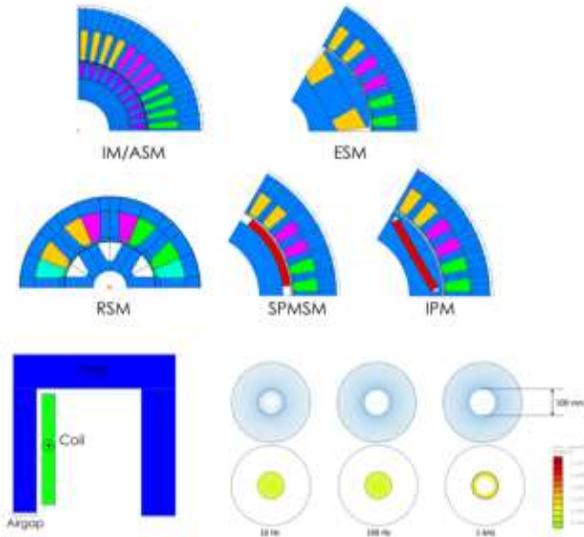
Mature & Accurate: under development since 1982

Flexible: model all motor types or general e-mag problems

Multi-physics: includes 2D thermal & mechanical modeling



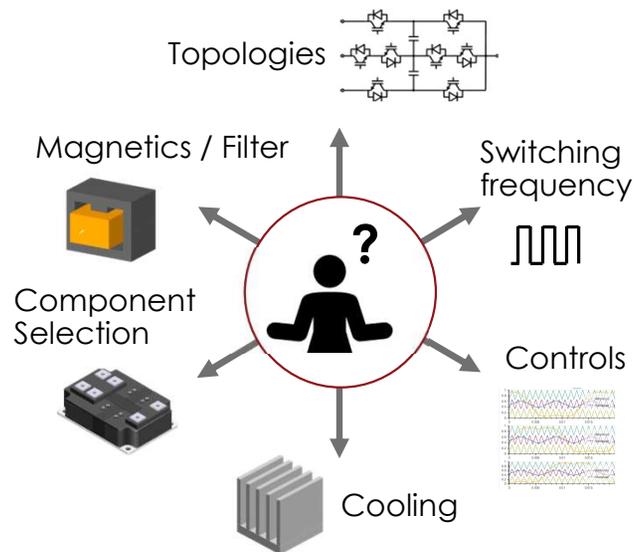
Dr.-Ing. Konrad Reichert
2006 IEEE Nikola Tesla Award



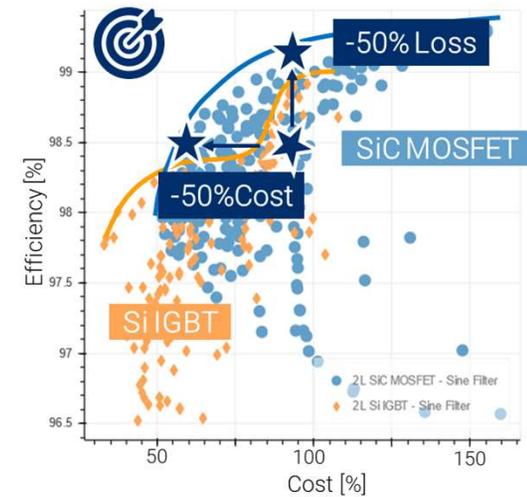
GT-PowerForge

GT-PowerForge for converter design stage:

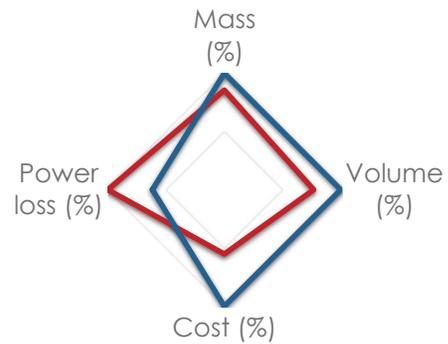
Power Converter Design Parameters



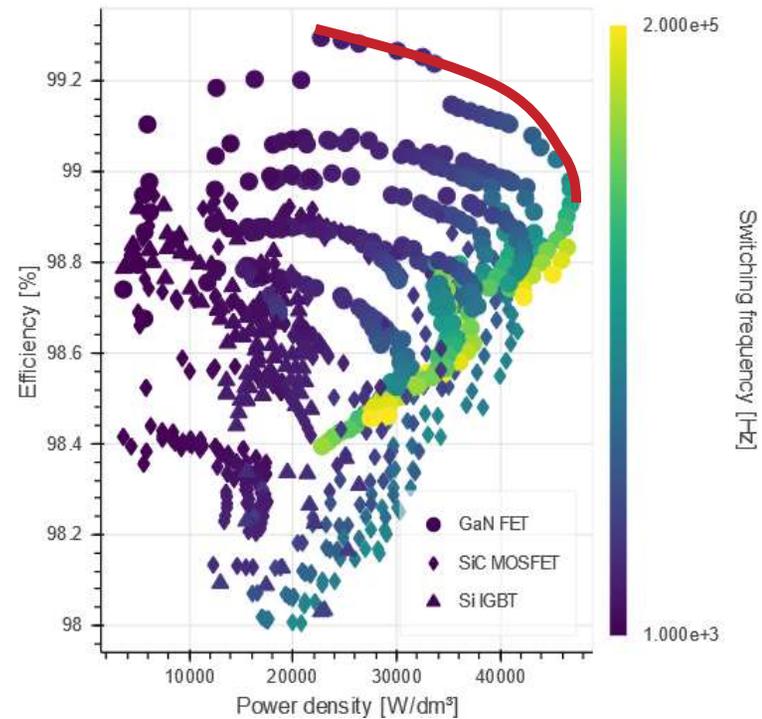
How to properly explore design space?



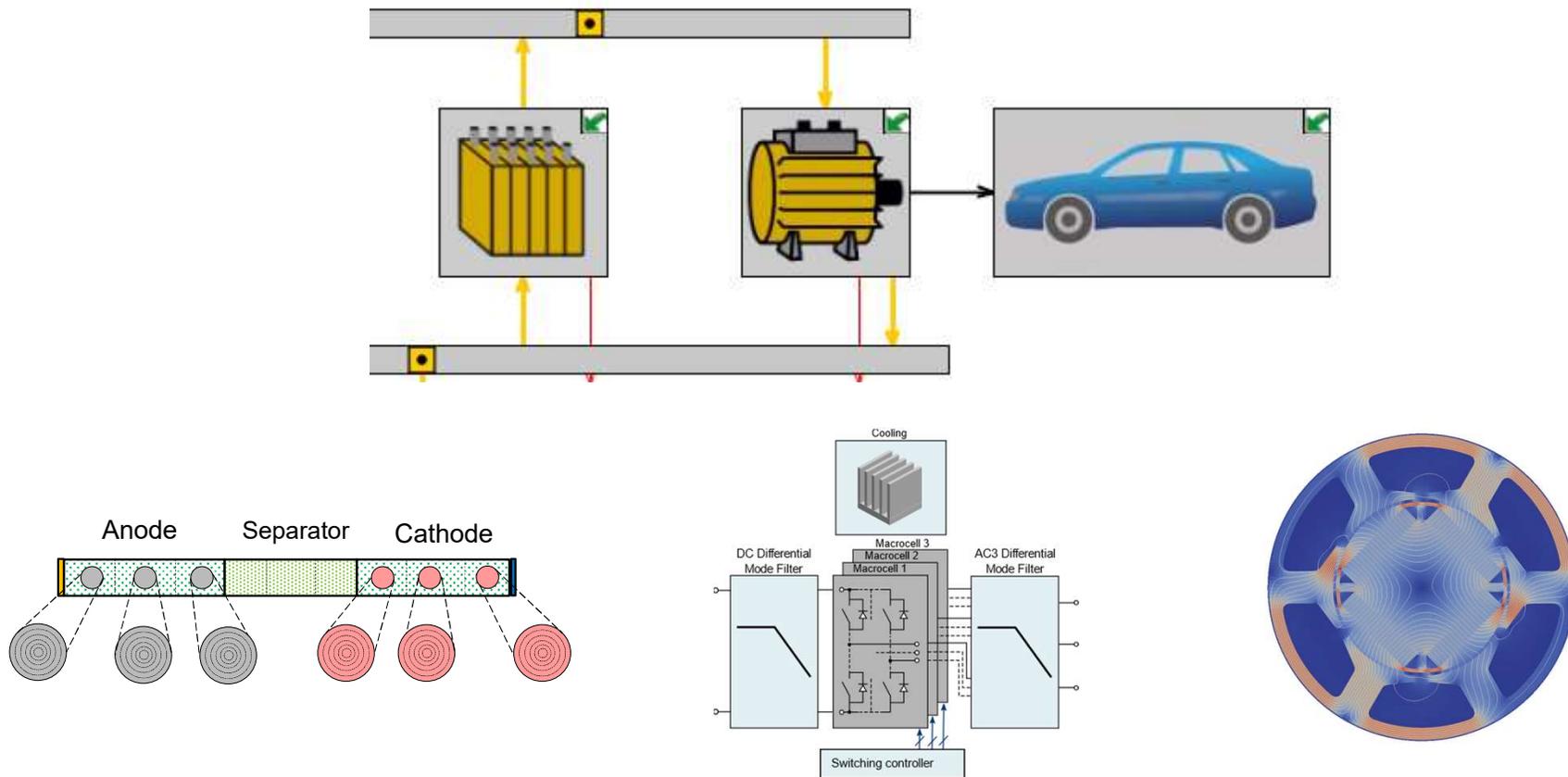
More Accurate Benchmark solutions



Efficiency - Weight -
Volume - Cost
Power density - Specific
power



E-Powertrain Design Analysis in GT-SUITE





Application Example

Reference Powertrain



Vehicle

(Sedan body)

- C_d : 0.29
- FA: 1.95m²
- Tires: 215/50R17
- *Calculated mass*

Motor

- 8-Pole IPM
- *Number of stator slots*
- *Airgap*
- *Width of Magnets*

Battery

- Cell:
 - NCM811
 - 21700 cylindrical
 - 4.8 Ah
 - 3.5 V
- *Variable Pack*
 - *# Series Cells*
 - *# Parallel Cells*

Inverter

- *2 options:*
 - *SiC MOSFET*
 - *Si IGBT*

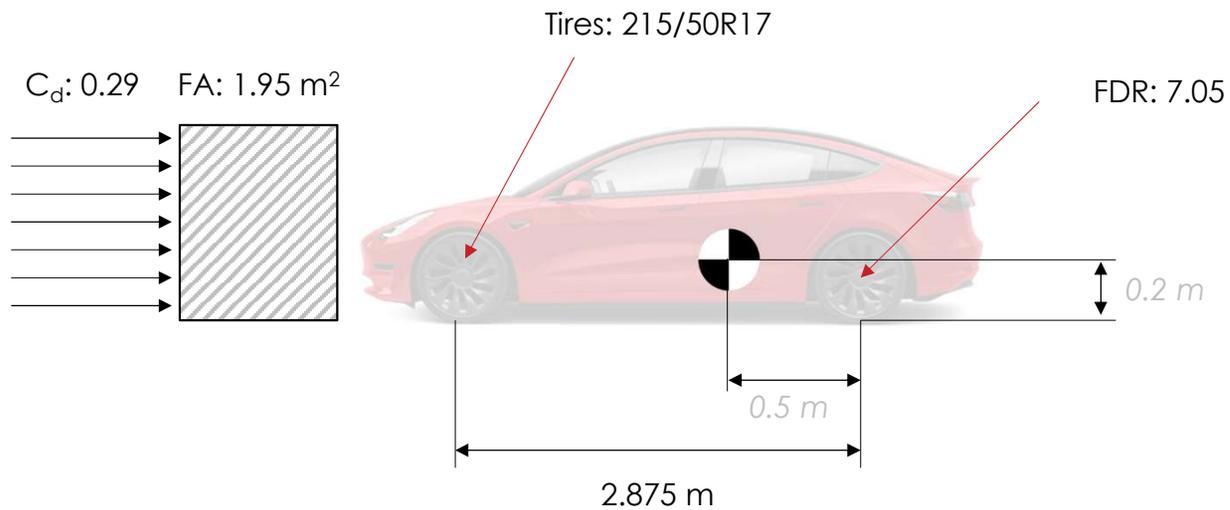
Legend

- Locked Parameter
- *Parameter to Vary*

Vehicle



Parameters for vehicle model include:



Mass of Vehicle: 1250 kg + Battery Mass

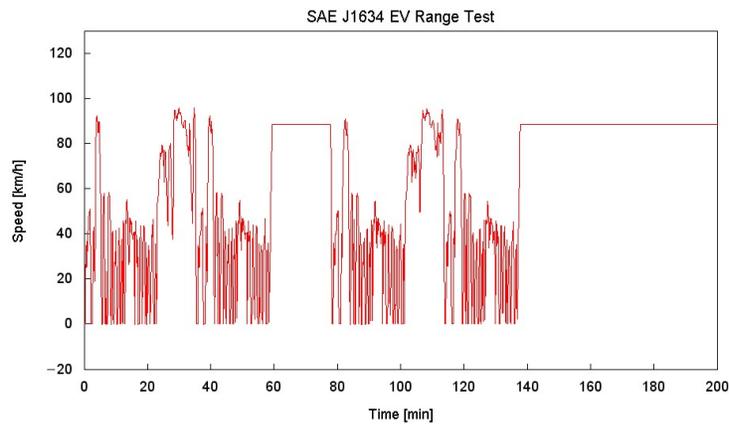
Assumed Values

Vehicle Model Tests & Metrics

Two tests setup to calculate vehicle-level metrics

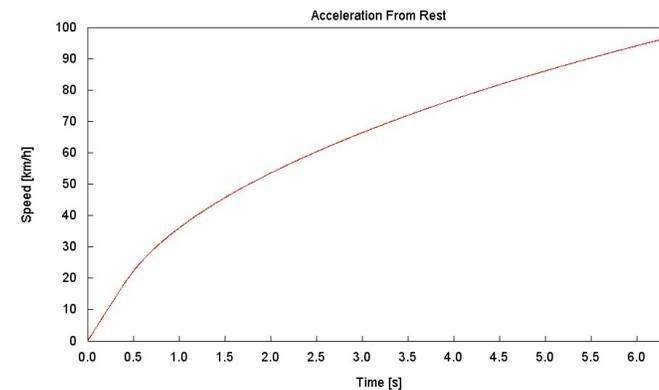


Vehicle Range



- BEV Range
- BEV Efficiency (kWh/100km)

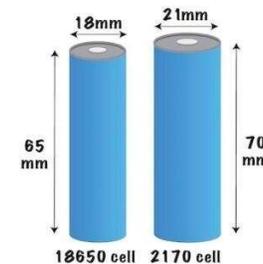
Acceleration test



- Time to Distance (0-100 kph)
- ¼ mile (400m, time, max speed)
- Top Speed

Lithium-ion cell

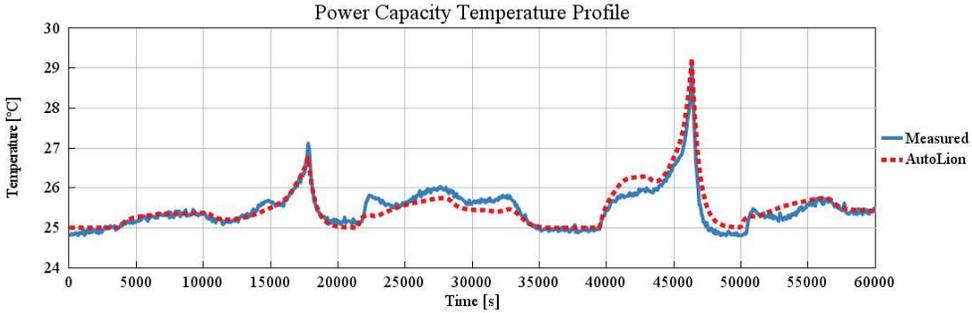
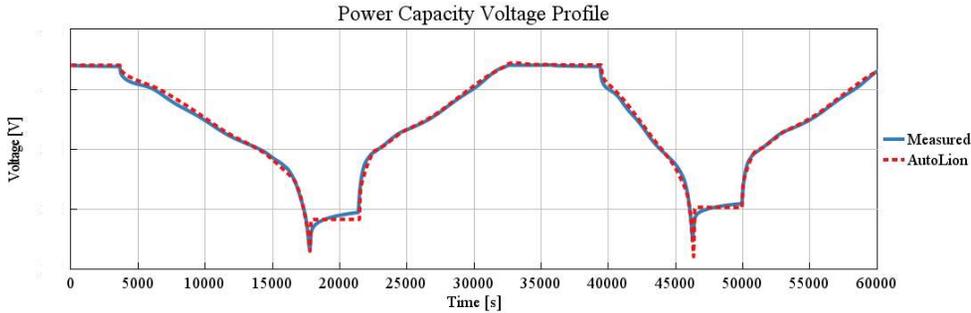
- NCM811 Cathode, Graphite Anode
- 21700 cylindrical
- 4.8 Ah
- 3.5 V
- **~70 grams** per cell
 - We assume **~110 grams** per cell for pack
 - Integration Factor of about **60%** to account for busbars, cooling strategy, BMS, etc.
- **€1.25** per cell



Battery Model



Using cell dimensions, AutoLion material database, and experimental results*, AutoLion model was calibrated**



— Measured
- - - AutoLion

* Experimental results provided by Southwest Research Institute's battery testing consortium, Electrified Vehicle and Energy Storage Evaluation (EVESE)

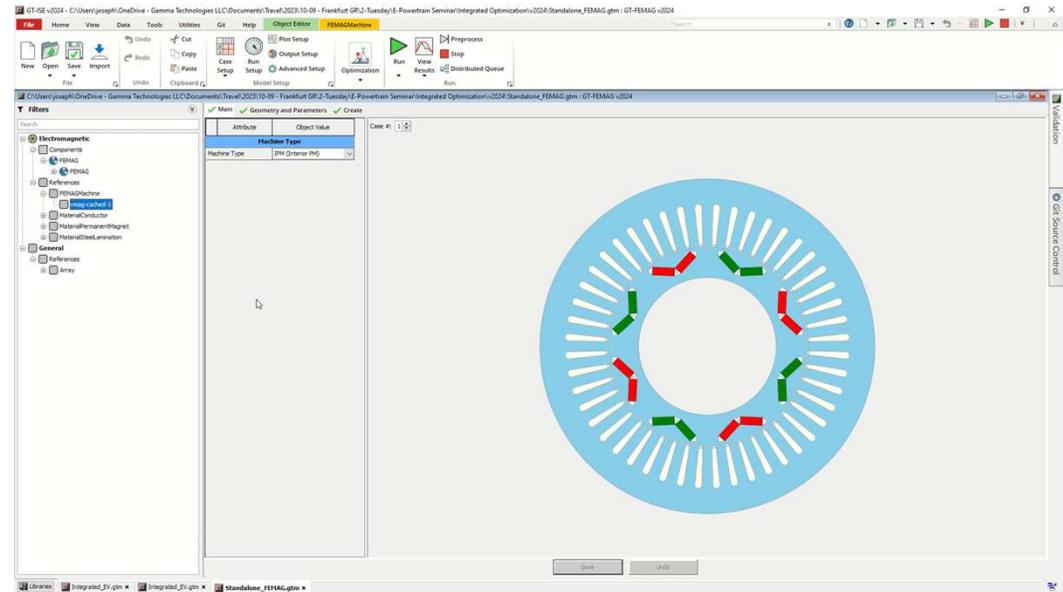


Traction Motor

Baseline IPM Design



Main Motor Parameters	
Motor Type	IPM (internal permanent magnet)
Magnet Shape	V-style
Number of stator slots	48
Number of pole pairs	4
Number of phases	3
Outer Diameter	270 mm
Bore Diameter	162 mm
Length	84 mm



Traction Motors

8 Total Designs to be compared at vehicle-level



Design Option	Baseline Option	Advanced Option	Additional Cost
Number of Stator Slots	24 Slots	48 Slots	€200
Magnet Width	18 mm	25 mm	€600
Airgap	1.5 mm	0.75 mm	€200

Traction Motor

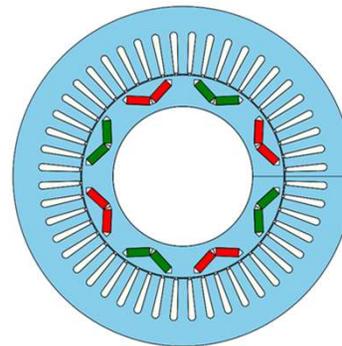
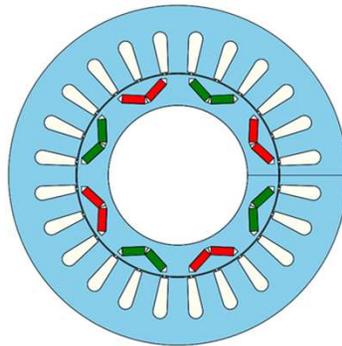
Using 8 Different Traction Motor Designs



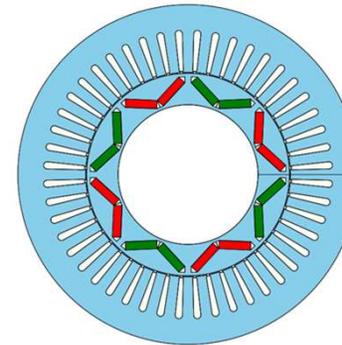
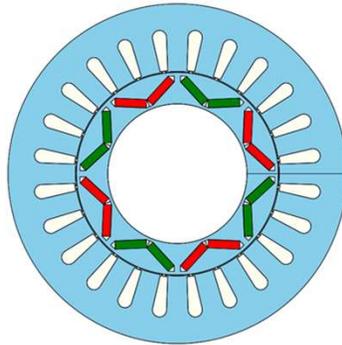
24 Stator Slots

48 Stator Slots

Small Magnets
(18mm width)



Large Magnets
(25mm width)



x 2 different air gaps
(0.75 mm, 1.5 mm)

Traction Inverter Design

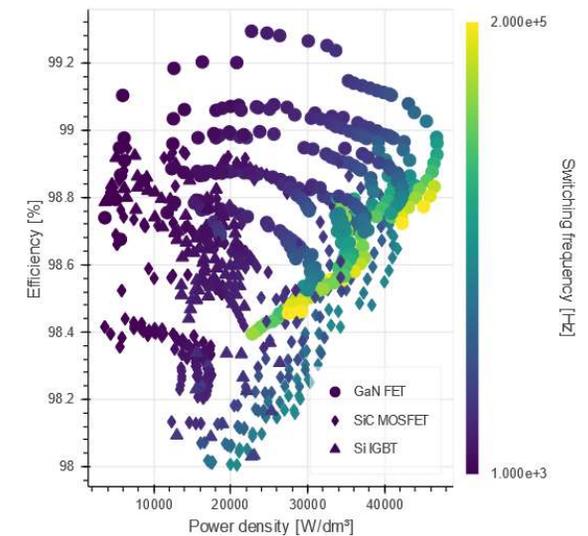


Designed & Analyzed over **3,016 designs** in an afternoon

- 28 switches
 - 9 Si IGBTs
 - 16 SiC MOSFETs
 - 3 GaNs
- 10 switching frequencies
- # Parallel Switches: 1, 2, 3, 4
- Space Vector & Sine PWM
- 2-level & 3-level topologies

Benchmark results Sweep history

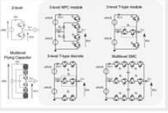
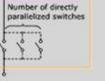
<input type="checkbox"/> Name
<input type="checkbox"/> MOSDET SiC 2-level SV (640 designs)
<input type="checkbox"/> MOSFET SiC 2-level - SPWM (640 designs)
<input type="checkbox"/> GaN 3-level (456 designs)
<input type="checkbox"/> MOSFET Si 3-level (160 designs)
<input type="checkbox"/> MOSFET SiC 3-level (400 designs)
<input type="checkbox"/> IGBT (720 designs)



Traction Inverter(s)



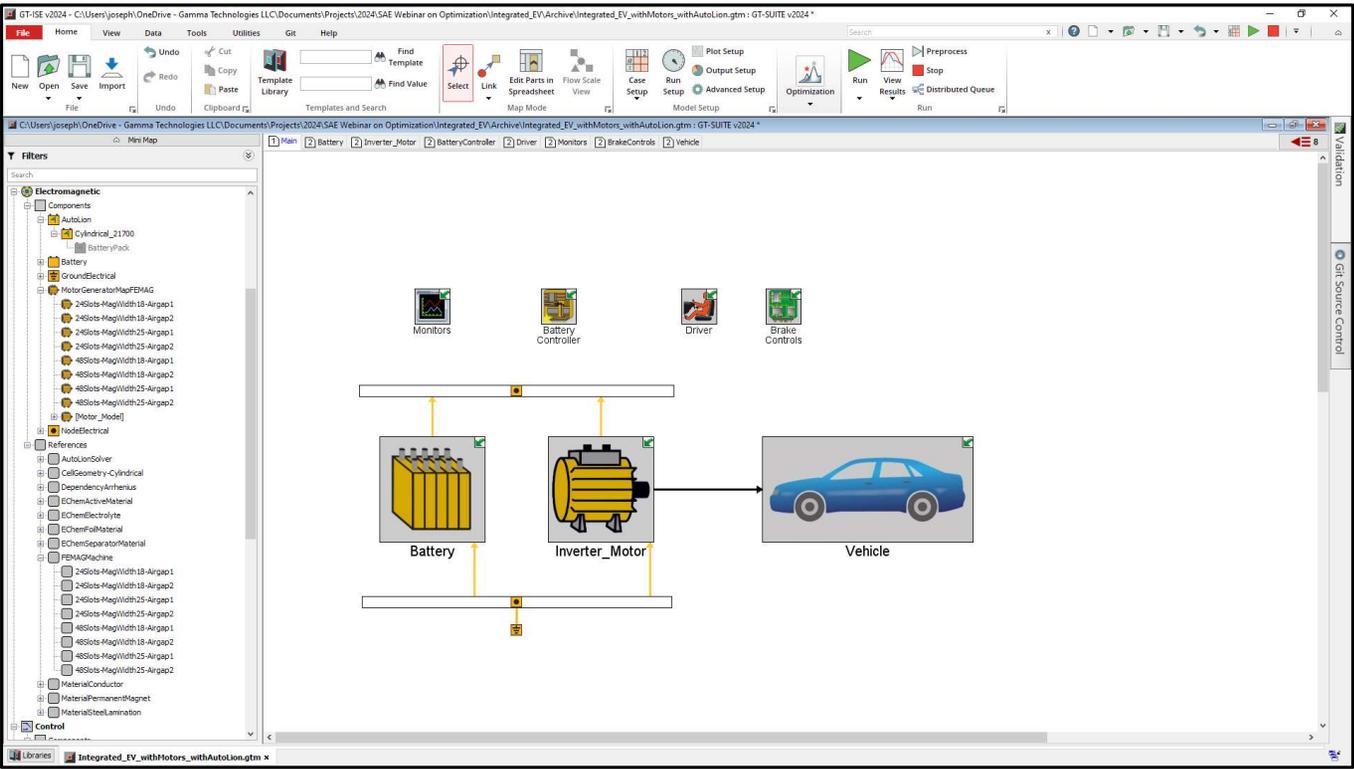
Exported maps for 2 Designs to be compared at vehicle-level

		Design 1	Design 2
Switch Technology		SiC MOSFET	Si IGBT
Inverter Topology		2-level	2-level
# of directly parallelized switches		4	3
Switching Frequency		10 kHz	10 kHz
Modulation Strategy		Sine PWM	Sine PWM
Estimated cost		€800	€500

Integration



Battery, Inverter, and Motor integrated into vehicle model with controls in GT-SUITE





Integrated Model Results

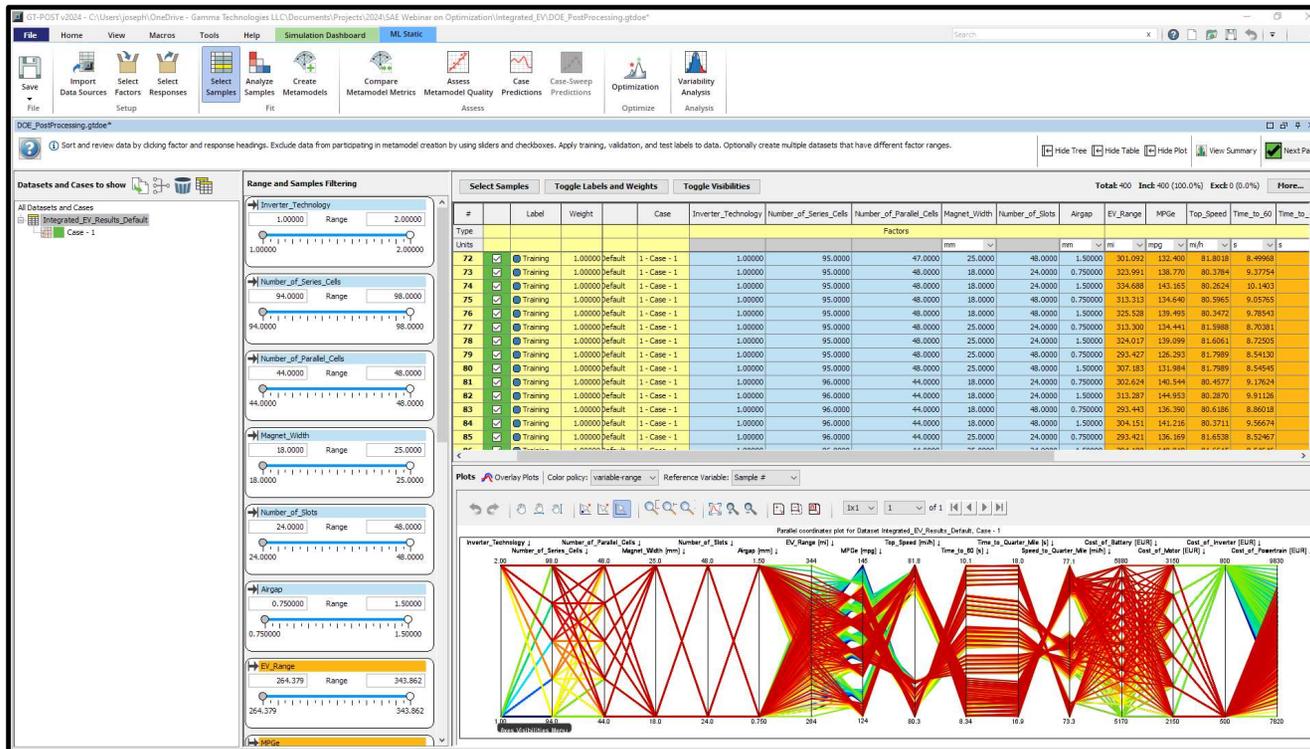
GT Design of Experiments

With GT Design of Experiments, setup a full factorial of electric powertrains, resulting in **400 powertrain designs** compared

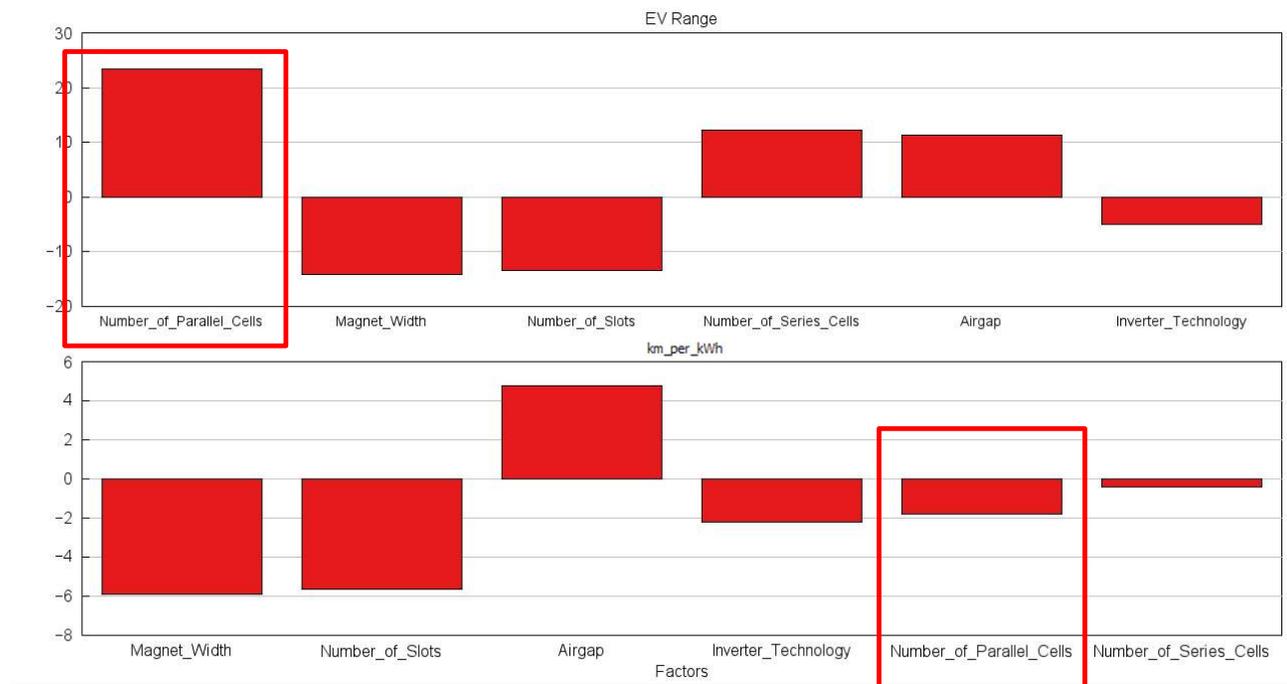
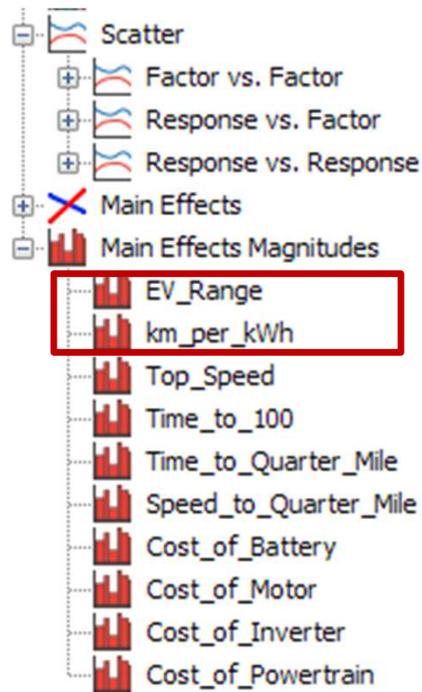
Factor	Number of Levels	Values
# Parallel Cells	5	44, 45, 46, 47, 48
# Series Cells	5	94, 95, 96, 97, 98
Inverter Technology	2	SiC MOSFET, Si IGBT
# Stator Slots	2	24, 48
Magnet Width	2	18mm, 25mm
Airgap	2	0.75 mm, 1.5 mm

GT Design of Experiments

Post-processed results with GT's built-in DOE Post-Processor

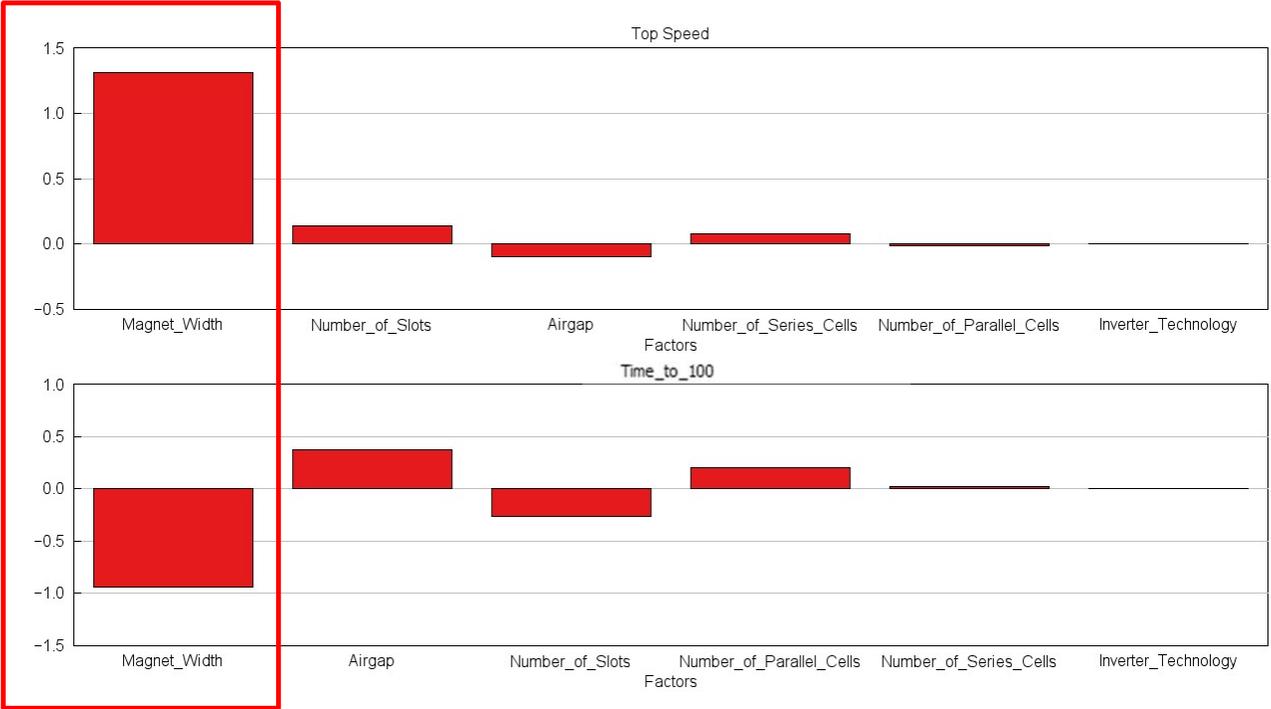
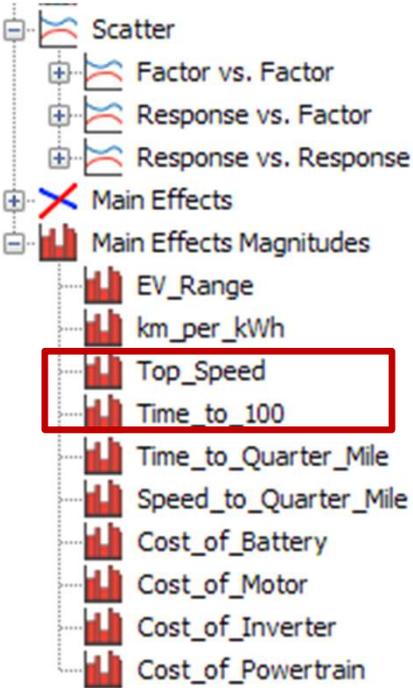


DOE Post-Processing: Sensitivity Analysis



0 - base line; x - advanced option; + - increase, - - decrease

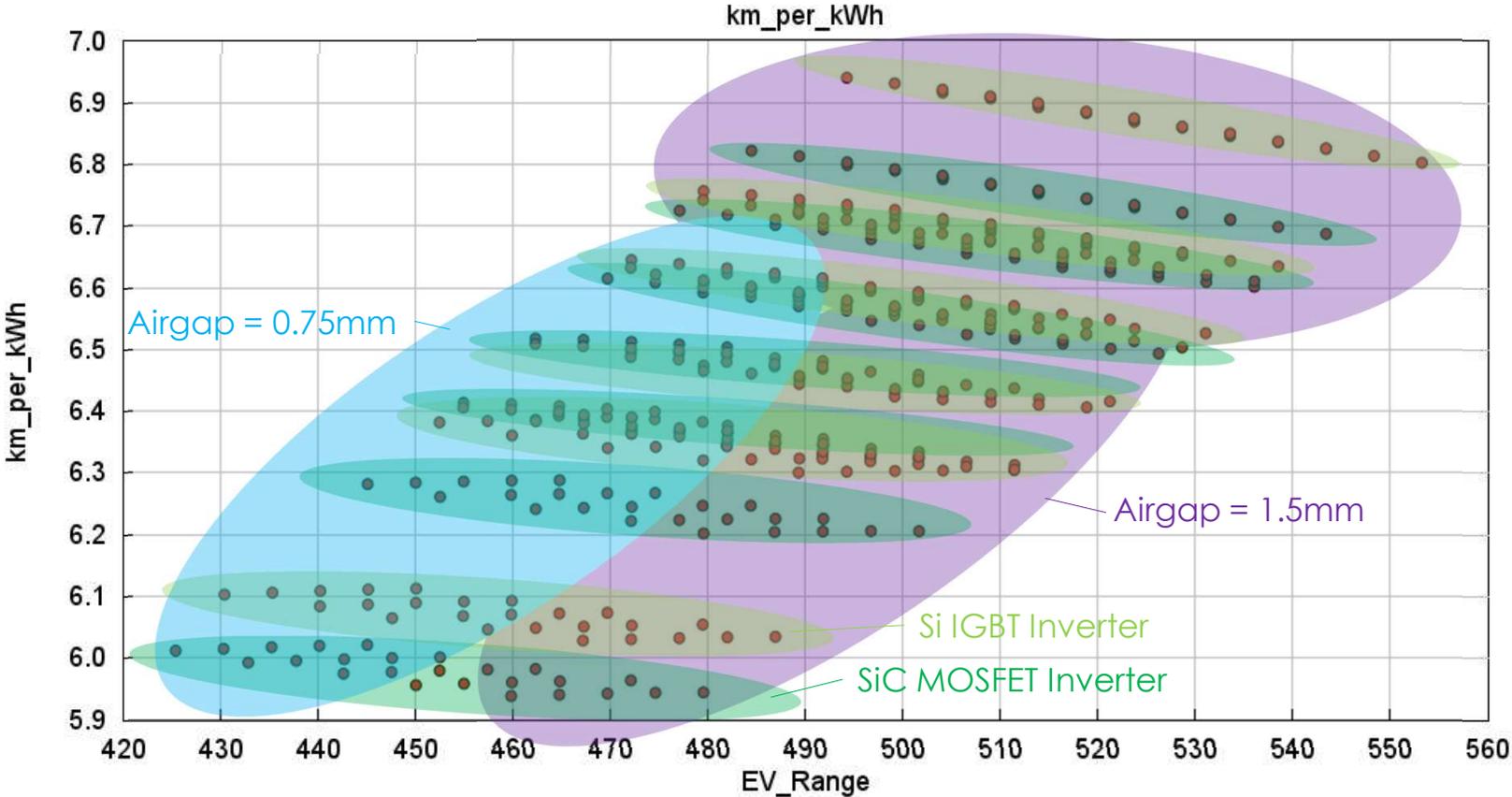
DOE Post-Processing: Sensitivity Analysis



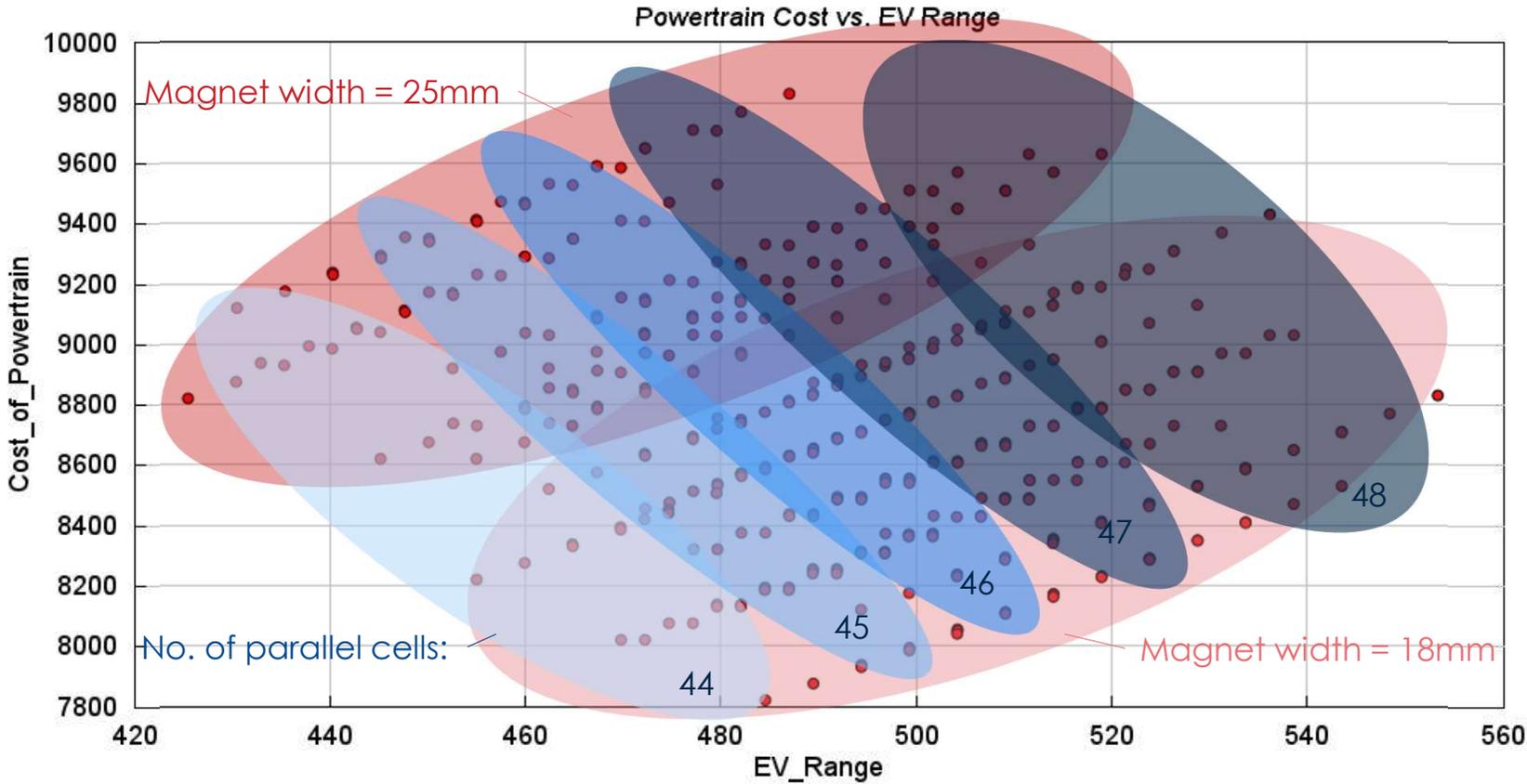
0 - base line; x - advanced option; + - increase, - - decrease



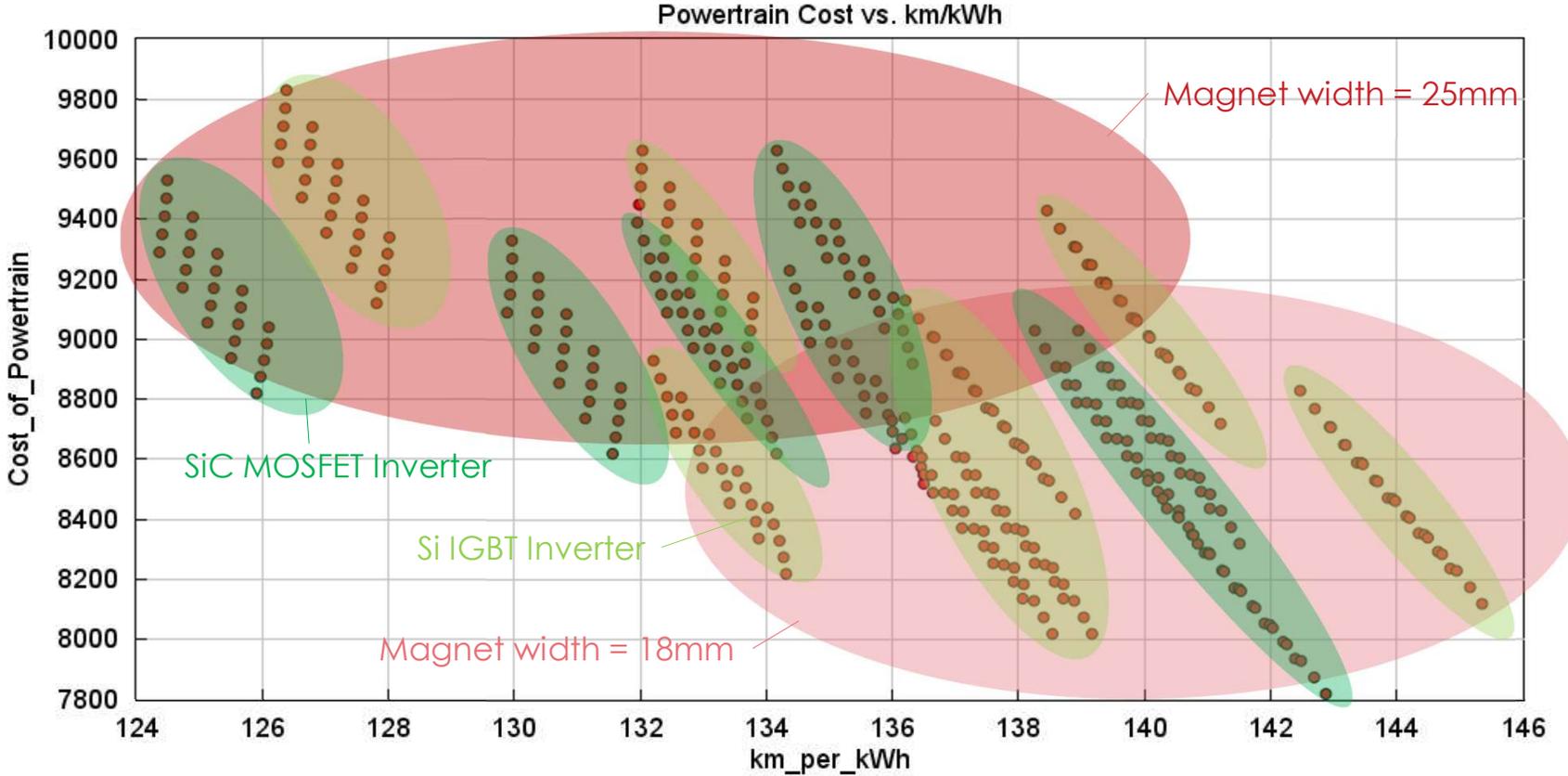
Response vs. Response Plots



Response vs. Response Plots

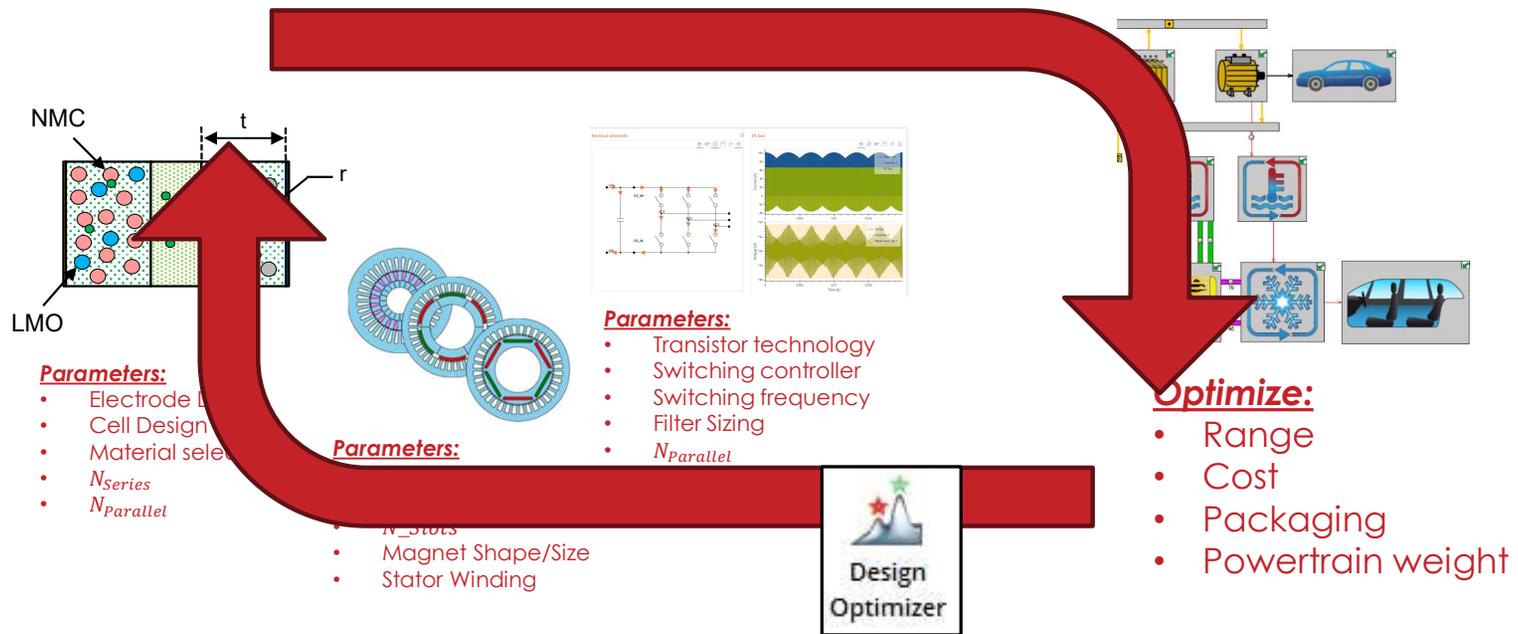


Response vs. Response Plots

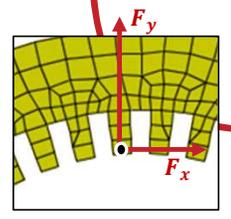
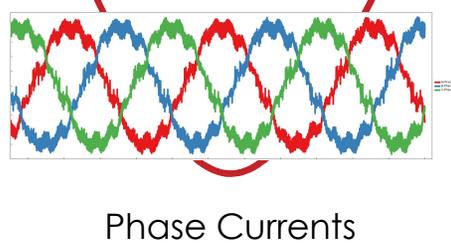
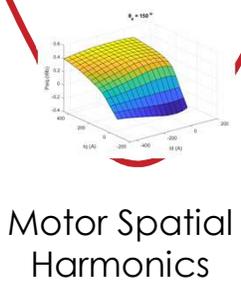
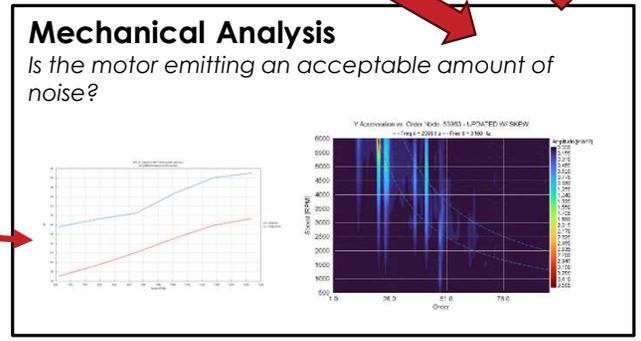
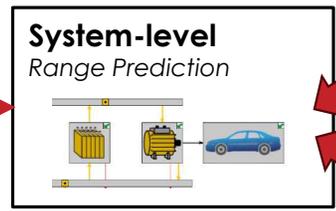
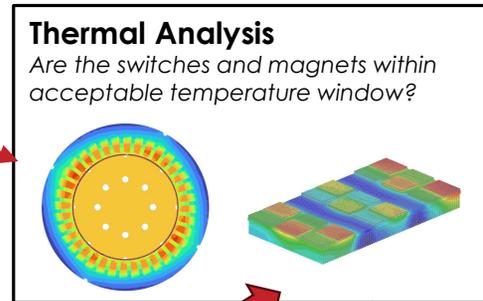
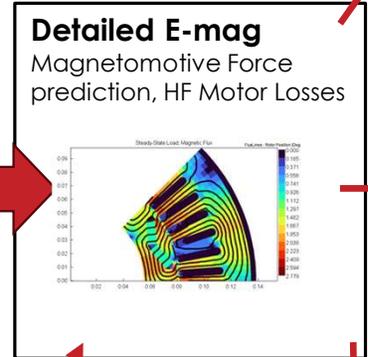
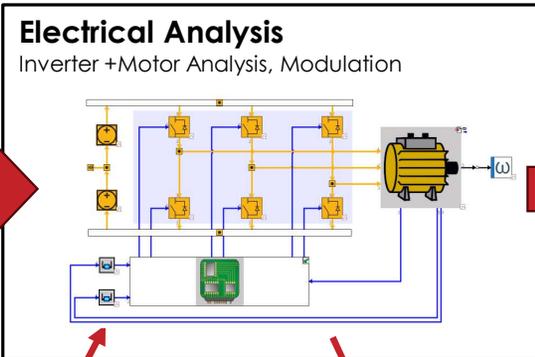
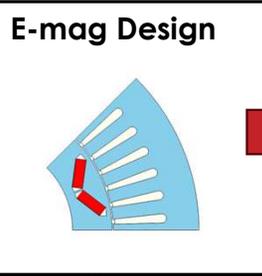
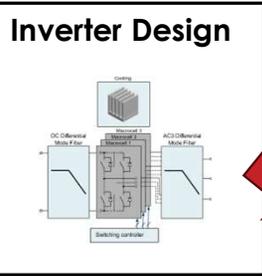


Expanding What's Possible

With GT-SUITE, GT-AutoLion, GT-FEMAG, and GT-PowerForge, explore system-level impact of component-level design space



Multi-physics Powertrain Optimization



Investigate Trade-offs!

